FURUNO

MAVpilot 300/711C

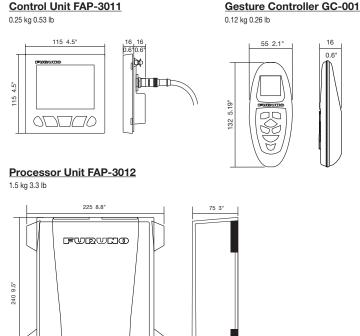




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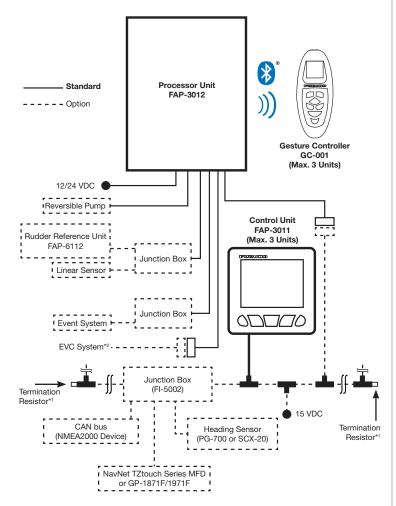
NAVpilot-300

NAVpilot-711C

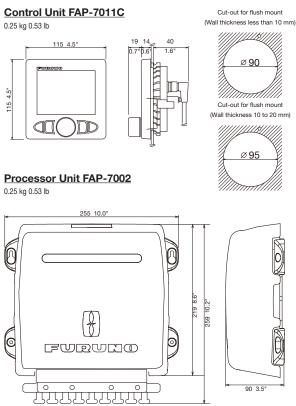


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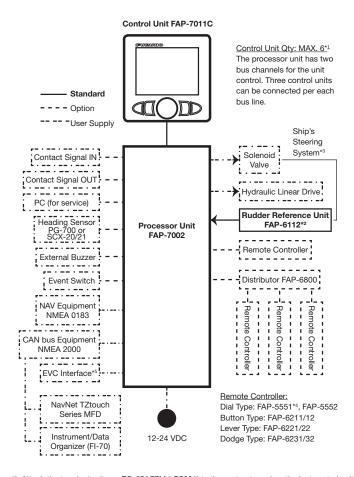
INTERCONNECTION DIAGRAM



- *1: Termination resistors must be installed at both ends of the backbone.
- *2: YANMAR VC10, SEASTAR SOLUTIONS OPTIMUS



INTERCONNECTION DIAGRAM



- *1: Attach the terminator (type: BD-07AFFM-LR7001) to the port not used on the last control unit in the series.
- *2: Not required for Fantum Feedback™.
- *3: Not required for a EVC system equipped vessel.
 *4: Connect one Dial-type Remote Controller FAP-5551 to one Distributor FAP-6800.
- *5: YANMAR VC10, SEASTAR SOLUTIONS OPTIMUS





























KEY FEATURES:

- ➤ Self-Learning and adaptive software; each time the boat goes to sea, the software learns the sea conditions and calculates the best adjustment for smooth steering
- ► Fantum Feedback[™] offers simplified installation while delivering enhanced steering control no need for physical rudder feedback unit
- ▶ Yanmar and Seastar VCS compatible
- Easy installation and smart network-based system configuration
- ► Waterproof Processing Unit (IP55) and Control Unit (IP56, IP65/67 for GC001)

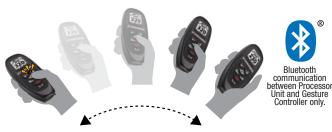
- ➤ Selectable "Economy" and "Precision" Navigation Modes combine adaptive technology, providing fuel and power savings of 2.5% or more*
- ► "Precision" provides tighter course keeping, within 0.01 NM of the set course
- Perfect for inboard or outboard power boats and sail boats (NAVpilot-711C only)
- ➤ Autopilot control available from NavNet TZtouchXL/TZtouch3/TZtouch2/ TZtouch/GP-1871F/1971F
- ► NEW! FishHunter[™] Drive delivers new control features for boaters utilizing select Suzuki outboard models (NavPilot-300 only)

^{*} Based on Furuno testing and "Scenarios for a Clean Energy Future 2000" - U.S. Department of Energy (https://www.nrel.gov/docs/fy01osti/29379.pdf)



Remote Navigation In The Palm of Your Hands (NAVpilot-300 only)

The Gesture Controller is a revolutionary and unique way to steer your boat remotely. By using Bluetooth signals, it is possible to control the Autopilot from anywhere on the boat within 10 meters. Just push and hold the button, point to the desired heading, and release the button to let the Autopilot redirect the boat!



Autopilot Control from NavNet TZtouch Series and GP-1871F/1971F

Furuno's NAVpilot Series are designed to match the GPS Chart Plotter GP-1871F/GP-1971F, the NavNet TZtouch Series, and other Furuno navigation equipment. The Plug and Play CAN bus interface allows for easy installation and exceptional interfacing.



SABIKI™ Mode for NAVpilot-300 and NAVpilot-711C

SABIKITM mode lets the Autopilot take control while you are drifting astern so you can focus on fishing instead of steering. When moving astern at a slow pace, SABIKITM mode is uniquely tailored for SABIKI fishing, jigging and bottom fishing. In order to maintain heading it is not sufficient to just reverse the engine and move astern. The steering has to be constantly adjusted in order to hold your heading. With SABIKITM mode turned on, the direction can be kept just by adjusting the throttle. SABIKI fishing requires a bit of technique and whether you just started or have considerable experience, SABIKITM mode will help you catch the bait fish needed for the big catch.









SABIKI™ mode is only user selectable if the current speed is below 5 knots. Once SABIKI™ mode is selected, the course can be set with the course knob and the arrow keys.

Compatible with EVC Engines

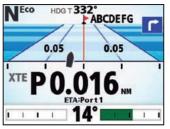
The NAVpilot-300/711C have the capability to work with Yanmar 8LV engine systems* and the Seastar Optimus360 Joystick system*.

FishHunter™ Drive for Suzuki Outboards

| Speed Control | The boat will maintain a constant speed, adjusting engine RPM as needed to account for changes in wind and tide. | |
|----------------------|--|--|
| Route Smoothing™ | Decreases the speed of turns at waypoints while navigating an active route. Reducing speed when executing a turn helps keep the vessel on course. | |
| Point Lock™ | Allows the vessel to easily maintain a fixed position by controlling the rudder and throttle, countering the effects of wind and tide, which are constantly working to move the boat. An invaluable tool for anglers to maintain a fixed position while fishing a wreck or reef, and for boaters who occasionally must wait for a bridge to open so they can pass. | |
| Auto Stop On Arrival | The NavPilot-300 automatically stops the vessel at the destination waypoint. When combined with the Point Lock™ feature, Auto Stop On Arrival allows the vessel to maintain a fixed position at the destination waypoint. | |
| SABIKI Lock™ | Expands upon the NavPilot-300's SABIKITM functionality by controlling both the rudder and throttle to maintain position, freeing the angler to focus 100% on jigging and other vertical fishing. | |
| | | |

Display Options for Day and Night

Several types of graphic displays are available, allowing you to customize the data to suit your own preferences with either digital or analog graphics. The NAVpilot-300 and NAVpilot-711C feature a color day/night graphic display, giving you better sunlight viewability during the day, while not affecting your night vision when the sun goes down.





Highway Mode Day

Highway Mode Night

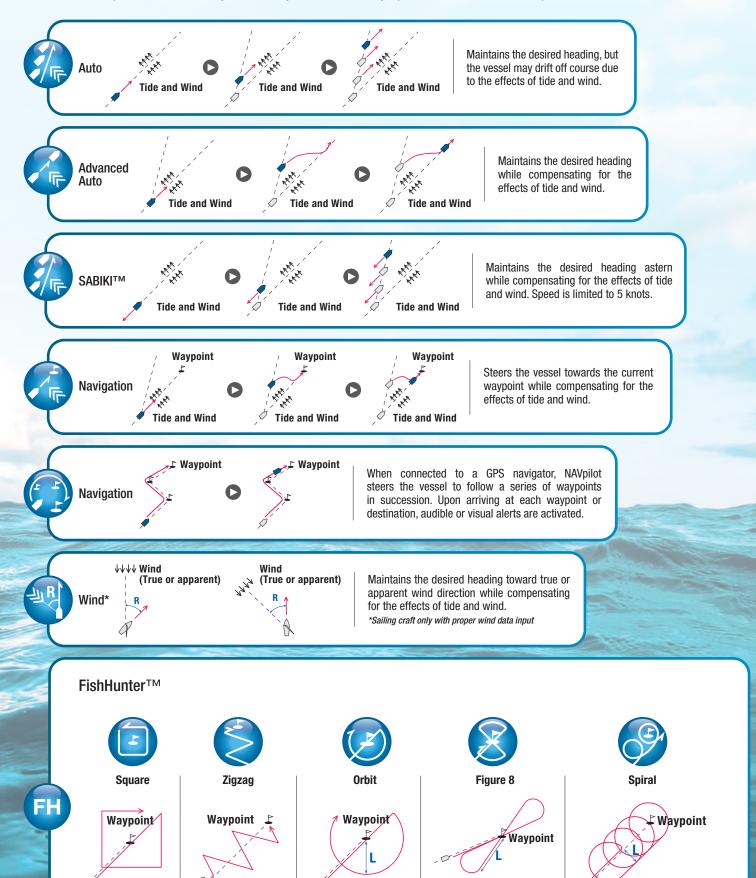




^{*} Required the optional IFNMEA2K2 to connect with NAVpilot-300/711C.

NAVpilot Offers Self-Learning and Adaptive Software

From the first dockside setup through the last voyage you made, NAVpilot continues to learn your vessel's steering characteristics. This allows dynamic adjustments to the boat's steering for vessel speed, trim, draft, tide and wind effects, weather, etc. These characteristics are stored in the processor's memory where they are continuously optimized to make the NAVpilot more versatile.



The NAVpilot will activate the FishHunter™ to perform various maneuvers around the target at a user-selected distance. The feature can also be used for Man Overboard (MOB).



SPECIFICATIONS (Page 2 of 2)

FURUNO

| | | Casa a f | | |
|--|----------------------|--|---|--|
| MODEL | | NAVpilot-300 | NAVpilot-711C | |
| CONTROL | LINUT | | | |
| | | | | |
| Screen Size | | | TFT color LCD | |
| Effective Dis | • • | , | V) x 61.92 (H) mm | |
| Screen Reso | olution | 320 x 2 | 240 dots (QVGA) | |
| Screen Brig | htness | 700 | cd/m ² typical | |
| Screen Con | trast | | 8 steps | |
| PROCESS | | | | |
| 11100200 | OH OHH | CTDV Auto Dodgo NELL (Non follow up) Turn CARIKITM | CTDV Auto Dodgo Turn Domoto CARIVIIM Advanced Auto* | |
| Steering Mo | ode | STBY, Auto, Dodge, NFU (Non-follow up), Turn, SABIKI™, FishHunter™, Advanced Auto*, Navigation* *External data required | STBY, Auto, Dodge, Turn, Remote, SABIKI TM , Advanced Auto*, Navigation*, Wind*, FishHunter ^{TM*} *External data required | |
| Weather Mode | | | Auto, Manual-Calm/Moderate/Rough | |
| Rudder Gain | | Auto/1-20 (Manual) | | |
| Counter Rudder | | Auto/0-20 (Manual) | | |
| Trim Gain | | Auto/1-20 (Manual) | | |
| | | -5° (port) to +5° (stbd) | | |
| Trim Adjustment | | , , , , | | |
| Change Course Speed | | 1-20 deg/s | 1-30 deg/s | |
| Rudder Angle Settings | | | 10-45 deg | |
| Alarm | | Heading deviation, Watch | Heading deviation, Cross-track error*, Ship's Speed*, Depth*, Water temperature*, Wind*, Watch, Log Trip* *External data required | |
| Motor Drive | | 10 A continuous, 20 A for 5 seconds | 25 A continuous, 50 A for 5 seconds | |
| | CONTROLLER (N | • | | |
| | • | • | | |
| | e/Resolution | 1.28" Monochrome TFT LCD, 128 x 128 pixels | | |
| Communica | tion Distance | 10 m (depending on environmental conditions) | | |
| INTERFAC | E | | | |
| Б., | | NMEA2000 x1, CAN bus x1 (DBW control). | NINEACTOR OF CAME AND A COLUMN | |
| Ports | | Contact signal x3, Bluetooth (Gesture Controller) | NMEA0183 x2, CAN bus x1, Contact signal x2 | |
| Input | NMEA0183 | | AAM, APB, BOD, BWC, BWR, DBT, DPT, GGA, GLL, GNS, HDG, HDM, HDT, MTW, MWV, ROT, RMB, RMC, THS, TLL, VHW, VTG, VWR, VWT, XTE, ZDA | |
| | NMEA2000 | 059392/904, 060160/416/928, 061184, 065240, 126208/464/720/992/996, 127237/250/258, 128259, | 059392/904, 060928, 061184,126208/720/992/996, 127250/251/258/488/489,128259/267, 129025/026/029/033/283/284/285, | |
| | NMEA0183 | 129025/026/029/283/284/285/538, 130577/818/821/827/841 | 130306/310/311/312/313/314/577818/821/827/880 DBT, DPT, GGA, GLL, GNS, HDG, HDM, HDT, MTW, MWV, RMB, | |
| | | | RMC, ROT, RSA, VHW, VTG, VWR, VWT, ZDA | |
| Output | NMEA2000 | 059392/904, 060928, 126208/464/720/993/996/998, 127237/245, 130816/821/822/823/827/841 | 059392/904, 060928, 061184, 126208/464/720/992/996, 127237/245/250/251/258, 128259/267, 129025/026/029/033/283/284/285, 130306/310/311/312/822/823/827 | |
| ENVIRON | MENT | | | |
| Temperature | 9 | -15 | 5°C to +55°C | |
| Temperature | | Processor Unit: IP55 | | |
| Waterproofing | | Control Unit: IP56 Gesture Controller: IP65/67 | Processor Unit: IP20 Control Unit: IP56 | |
| POWER SUPPLY | | | | |
| Processor Unit | | 12-24 VDC 0.22 A max. (LEN: 2) | 12-24 VDC: 4.0-2.0 A (control unit: 6 sets), excluding pump | |
| Control Unit | t | 15 VDC 0.29 A max.(LEN: 6) | | |
| Gesture Controller | | VDC, Dry cell battery (AAA x2) | | |
| EQUIPMENT LIST | | | | |
| | | | | |
| Standard | | Control Unit (FAP-3011), Processor Unit (FAP-3012), Gesture Controller (GC-001), Installation Materials, Accessories, and Spare Parts | Control Unit (FAP-7011C), Processor Unit (FAP-7002), Rudder Reference Unit (FAP-6112), Integrated Heading Sensor (PG-700), Installation Materials and Spare Parts | |
| Options | | Control Unit (FAP-3011), Gesture Controller (GC-001), Bracket-mount Kits, Cables, Connectors, Junction Box, Pump Unit, Rudder Reference Unit | Control Units, Flush Mount Kits, Bracket-mount Kits, Cradle, Rudder Reference Units (FAP6112-200), Remote Controllers, Cables, Connectors, Junction Box, Pump Unit | |
| FighHunto | rTM Drivo - Pofor to | online flyer for more information | | |
| I ISIII Iuiite | Dilve - Helei lo | online tryet for more information | | |
| Engine | | Suzuki Outboards | DF140BG/115BG, DF200AP/175AP/DF150AP, DF300AP/250AP, DF350A/325A*/300B *Not Available in US | |
| | | Supported Quantity | Maximum 4 units | |
| Autopilot | | NAVpilot-300 | | |
| Display Device | | NavNet TZtouchXL series – TZT10X/13X/16X/22X/24X ver. TBD NavNet TZtouch3 series – TZT9F/12F/16F/19F ver. TBD NavNet TZtouch2 series – TZTL12F/L15F/2BB ver. TBD GP1871F/1971F – ver. TBD SMD series – SMD7/9 ver. TBD and SMD12/16 ver. TBD For active route output to SUZUKI engines, autopilot mode display, etc. | | |
| Navigation Data Heading, position, and vessel speed sensors for autopilot control | | rol C-2503LB | | |
| | | | | |

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